

Network Formation: Bilateral Contracting and Myopic Dynamics

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Objectives

Goal: Design *intuitive* dynamics that converge to “good” equilibria of Network Formation Games

Setting:

- ▶ Data networks
- ▶ Contracting
- ▶ Pairwise Stability

Examples:

- ▶ The Internet at the ISP level
- ▶ Mobile ad-hoc Networks

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Utility Model

For node $i \in V$, sum of three terms:

- ▶ Maintenance cost per edge of $\pi > 0$
- ▶ Routing cost of $c_i \geq 0$ per packet forwarded or received
- ▶ Disconnectivity cost of $\lambda > 0$ per unreachable node

Notation: cost to i in network topology G is $C_i(G)$

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Edges in G result from *contracts* between nodes

- ▶ common business tool
- ▶ captures current value of link

Contract (i, j) : utility transfer of $Q(i, j; G)$ from i to j

Example: Rubinstein Bargaining

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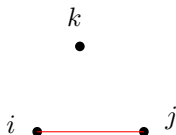
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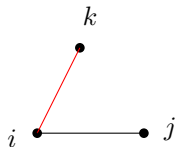
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Why Contracting?

Contracting induces payment *that remains fixed* until re-negotiation of contract.



i pays $Q(i, j; G + ij)$ to j



i pays $Q(i, j; G + ij)$ to j

and

$Q(i, k; G + ij + ik)$ to k

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Payment Matrix, Contracting Graph and Total Utility

We keep track of

- ▶ payments in a *payment matrix* P ;
- ▶ contracts in a *contracting graph* Γ

Thus the state of the network is given by the network topology G , the contracting graph Γ and the payment matrix P , and the total utility to node i is

$$U_i(G, P) = \sum_{j \neq i} (P_{ji} - P_{ij}) - C_i(G)$$

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Static Game

Pairwise Stability

One-shot static game.

- ▶ Each node selects nodes to propose contracts to;
and
- ▶ selects nodes it accepts contracts from.
- ▶ Successful contract induces link.

Let G be the resulting topology.

- ▶ We set $P_{ij} = Q(i, j; G)$ if $(i, j) \in \Gamma$, and zero otherwise.

Definition (Pairwise Stability)

An outcome of the game is pairwise stable if it is a N.E.
and no two players can benefit from a bilateral deviation.

Note: We only update the payments of the contracts
involved in the deviation.

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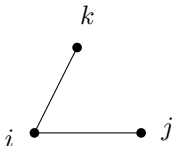
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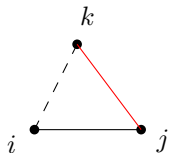
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Deviation Example



i pays $Q(i, j; G)$ to j

i pays $Q(i, k; G)$ to k



i still pays $Q(i, j; G)$ to j

k pays $Q(k, j; G - ik + kj)$ to j

Assume that k and j jointly deviate. k removes all contracts with i , and proposes (k, j) to j , and j accepts. Note that the payment from i to j did not change

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Two-Stage Dynamics

A node u first unilaterally deviates with respect to some edge uv (stage 1), and then bilaterally deviates with some node w chosen by u (stage 2)

Why two stage dynamics?

“Unilateral deviation increases bargaining power”.

↪ Allows node u to create a favorable intermediate state so that w accepts u 's offer *even* if w 's utility decreases.

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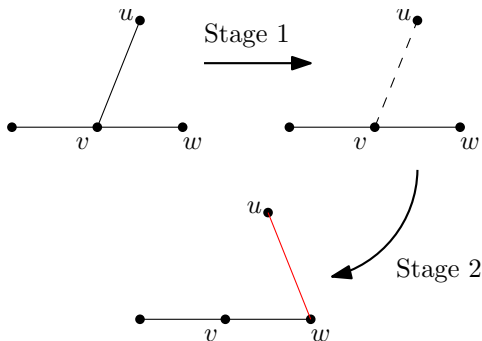
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Example



Here one can see that, in all likelihood, w 's utility at the end of the round is lower than at the beginning.

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Assumptions and Convergence

- ▶ Disconnectivity cost large enough to ensure connectivity
- ▶ Contracting function is
 - ▶ monotone and
 - ▶ anti-symmetric.

Definition (Convergence)

Given any initial outcome of the static game, we say the dynamics *converge* if, almost surely, there exists K such that, for $k > K$

$$\left(G^{(k+1)}, \Gamma^{(k+1)}, P^{(k+1)} \right) = \left(G^{(k)}, \Gamma^{(k)}, P^{(k)} \right)$$

Convergence Theorem

Theorem

For any activation process, the dynamics initiated at any outcome of the static game converge. Further, if the activation process is a uniform activation process, then the expected number of rounds to convergence is $O(n^5)$.

Given an activation sequence, the limiting state is such that:

- 1. the network topology is a tree where any node that is not a leaf is of minimum routing cost.*
- 2. It is a pairwise stable outcome of the static game.*

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Second Convergence Theorem

During the first stage, exogenously remove the link with some probability.

Then the dynamics converge *even without anti-symmetry*.

Given an activation sequence, the limiting states are such that:

1. the network topology is a tree where any node that is not a leaf is of minimum routing cost.
2. All visited states are pairwise stable outcomes of the static game.

Important Corollary

If there is a unique node of minimum routing cost v_{\min} , then the dynamics converge to the star centered at v_{\min} .

Any star centered at a node of minimum routing cost minimizes the *price of stability*.

Thus, in this particular case, our dynamics select *the most efficient* pairwise stable outcome.

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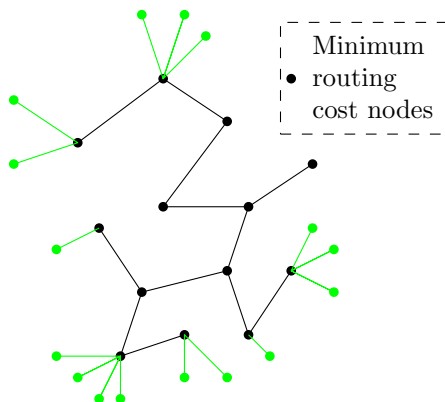
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Selecting “Good” Networks

What happens if we have several nodes of minimum routing cost?



In the limiting state, all traffic is routed by minimum routing cost nodes.

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We are extending our results to other settings.

- ▶ We can generalize the first stage of the dynamics.
- ▶ We can constrain the set of possible nodes to a ℓ -neighborhood of the active node.
- ▶ Finally, under a reasonable tie-breaking rule, we can assume that $\pi = 0$.

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Comments?
Questions?

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Thank you

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